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## THE KOLMOGOROV EQUATION WITH TIME-MEASURABLE COEFFICIENTS

JAY KOVATS

ABSTRACT. Using both probabilistic and classical analytic techniques, we investigate the parabolic Kolmogorov equation

$$L_t v + \frac{\partial v}{\partial t} \equiv \frac{1}{2} a^{ij}(t) v_{x^i x^j} + b^i(t) v_{x^i} - c(t) v + f(t) + \frac{\partial v}{\partial t} = 0$$

in  $H_T := (0, T) \times E_d$  and its solutions when the coefficients are bounded Borel measurable functions of  $t$ . We show that the probabilistic solution  $v(t, x)$  defined in  $\bar{H}_T$ , is twice differentiable with respect to  $x$ , continuously in  $(t, x)$ , once differentiable with respect to  $t$ , a.e.  $t \in [0, T)$  and satisfies the Kolmogorov equation  $L_t v + \frac{\partial v}{\partial t} = 0$  a.e. in  $\bar{H}_T$ . Our main tool will be the Aleksandrov-Busemann-Feller Theorem. We also examine the probabilistic solution to the fully nonlinear Bellman equation with time-measurable coefficients in the simple case  $b \equiv 0, c \equiv 0$ . We show that when the terminal data function is a paraboloid, the payoff function has a particularly simple form.

### 1. INTRODUCTION

It is well-known in the theory of diffusion processes [2, 3] that when  $g \in C^2(E_d)$  and the coefficients  $a(t, x)$ ,  $b(t, x)$ ,  $c(t, x)$  and free term  $f(t, x)$  are sufficiently smooth in  $(t, x)$  and satisfy certain growth conditions, with  $c(t, x) \geq 0$ , then the function

$$v(t, x) = \mathbf{E} \left[ \int_t^T f(r, \xi_r(t, x)) e^{-\varphi_r(t, x)} dr + e^{-\varphi_T(t, x)} g(\xi_T(t, x)) \right], \quad (1.1)$$
$$\varphi_s(t, x) = \int_t^s c(r, \xi_r(t, x)) dr$$

belongs to  $C^{1,2}(H_T)$  and satisfies the Kolmogorov equation  $Lv(t, x) + \frac{\partial v}{\partial t}(t, x) = 0, \forall (t, x) \in \bar{H}_T$ , where  $Lv := \frac{1}{2} a^{ij}(t, x) v_{x^i x^j} + b^i(t, x) v_{x^i} - c(t, x) v + f(t, x)$ , with  $v(T, x) = g(x)$ . In (1.1), for fixed  $(t, x) \in \bar{H}_T$ ,  $\omega \in \Omega$  and  $s \geq t$ ,  $\xi_s(t, x) = \xi_s(\omega, t, x)$  is the solution of the stochastic equation  $\xi_s = x + \int_t^s \sigma(r, \xi_r) d\mathbf{w}_r + \int_t^s b(r, \xi_r) dr$ , where  $(\Omega, \mathcal{F}, P)$  is a complete probability space on which  $(\mathbf{w}_t, \mathcal{F}_t)$  is a  $d_1$ -dimensional Wiener process, defined for  $t \geq 0$ . Furthermore,  $\sigma(t, x)$  and  $b(t, x)$  are assumed continuous in  $(t, x)$  and have values in the set of  $d \times d_1$  matrices,  $E_d$  respectively, with  $a = \sigma \sigma^*$ . The fact that the probabilistic solution  $v$  satisfies the

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Kolmogorov equation throughout  $\bar{H}_T$  is proved using Itô's formula and relies heavily on the continuity in  $t$  of the coefficients to establish the existence and continuity in  $(t, x)$  of  $\frac{\partial v}{\partial t}$  [3, Chapter 5]. In this paper, we show that if the coefficients are only bounded Borel measurable functions of  $t$ , the second derivatives  $v_{x^i x^j}(t, x)$  exist and are continuous in  $(t, x)$  (Theorem 2.1) but in general,  $\frac{\partial v}{\partial t}$  exists only in the generalized sense (Theorem 2.3) and the Kolmogorov equation will be satisfied only in the almost everywhere sense (Theorem 2.5). For example, consider the function  $v(t, x) = |x|^2 + 2d(\frac{1}{2} - t)_+$ . For  $t \neq \frac{1}{2}$ ,  $\frac{\partial v}{\partial t}(t, x)$  exists and equals  $-2dI_{0 \leq t < \frac{1}{2}}$  and hence for  $t \neq \frac{1}{2}$ ,  $v$  is a solution of the degenerate equation  $I_{0 \leq t < \frac{1}{2}} \Delta v + \frac{\partial v}{\partial t} = 0$  in  $[0, 1) \times E_d$ . Note  $\frac{\partial v}{\partial t}(t, x)$  is discontinuous in  $t$ .

When the coefficients and free term are independent of  $x$ , the right hand side of our stochastic equation is independent of  $\xi$  and the probabilistic solution (1.1) takes a decidedly more convenient form (see (3.4)). Since the other terms in (3.4) are independent of  $x$  and their derivatives with respect to  $t$  can be explicitly calculated (almost everywhere) it suffices to investigate the function  $v(t, x) = \mathbf{E}g(\xi_T(t, x))$ .

We do this in two ways. In section 1, we use probabilistic arguments to show that for  $g \in C^2(E_d)$ , the function  $v(t, x) = \mathbf{E}g(\xi_T(t, x))$  is twice differentiable with respect to  $x$ , continuously in  $(t, x)$  and once differentiable with respect to  $t$ , a.e.  $t \in [0, T)$ . We then apply the Aleksandrov-Busemann-Feller theorem to a variant of  $v$  to show that  $v$  satisfies the Kolmogorov equation  $\frac{1}{2}a^{ij}(t)v_{x^i x^j} + b^i(t)v_{x^i} + \frac{\partial v}{\partial t} = 0$  a.e. in  $H_T$ . From this it follows (by our previous remark) that the simplified version of (1.1), given by (3.4) satisfies the more general Kolmogorov equation a.e. in  $H_T$ . In section 2, we use the fact that  $\xi_T(t, x)$  is a Gaussian vector to express  $v$  as a convolution (in  $x$ ) of  $g$  with a kernel  $p$  which is the fundamental solution of the Kolmogorov equation (a.e.  $t$ ). Our proof that this convolution satisfies the Kolmogorov equation amounts to showing that we can differentiate the kernel under the integral sign. Here we assume only that  $g$  is continuous and slowly increasing, that is  $|g(x)| \leq C_1 e^{C_2|x|^2}$ . Our derivative estimates are done under the assumption that the coefficient matrix  $a(t)$  is non-degenerate. This assumption was not needed in section 1, (due to the assumption  $g \in C^2(E_d)$ ) yet we do get a slightly more refined result here, namely  $v(t, x) = \mathbf{E}g(\xi_T(t, x))$  satisfies the Kolmogorov equation for almost every  $t \in [0, T)$  and any  $x \in E_d$ . Finally in section 4, we examine the payoff function for the fully nonlinear Bellman equation in the simple case  $b \equiv 0$ ,  $c \equiv 0$ . It turns out that when  $g$  is a paraboloid, the probabilistic solution of the Bellman equation has a particularly simple form.

## 2. THE PROBABILISTIC APPROACH

Throughout this section, we assume the following.

Let  $g \in C^2(E_d)$  and assume that for all  $x, y \in E_d$ ,  $|g(x)|, |g_{(y)}(x)|, |g_{(y)(y)}(x)| \leq K(1 + |x|^m)$ , where for any twice differentiable function  $u(x)$  and  $l \in E_d$ ,  $u_{(l)}(x) = |l|^{-1}u_x(x) \cdot l$ ,  $u_{(l)(l)}(x) = |l|^{-2}l^*u_{xx}(x)l$ . For  $t \in [0, T]$  and  $x \in E_d$ , we define, for  $s \in [t, T]$ , the diffusion process  $\xi_s(t, x) = x + \int_t^s \sigma(r) d\mathbf{w}_r + \int_t^s b(r) dr$ , where the Borel measurable coefficients  $\sigma(t)$ ,  $b(t)$  are defined on  $[0, T]$ , independent of  $\omega \in \Omega$  and satisfy

$$\int_0^T [|\sigma(t)|^2 + |b(t)|] dt < \infty. \quad (2.1)$$

Under these assumptions, we prove our first theorem.

**Theorem 2.1.** For  $(t, x) \in \bar{H}_T$ , the function  $v(t, x) = \mathbf{E}g(\xi_T(t, x))$  is twice differentiable with respect to  $x$ , continuously in  $(t, x)$  and for any  $y, \bar{y} \in E_d$ ,  $v_{y\bar{y}}(t, x) = \mathbf{E}g_{y\bar{y}}(\xi_T(t, x))$ .

*Proof.* We show that  $v(t, x)$  is differentiable with respect to  $x$ . Writing  $\xi_T(t, x) = x + \eta_T(t)$ , where  $\eta_T(t) := \int_t^T \sigma(r) d\mathbf{w}_r + \int_t^T b(r) dr$ , note that for any  $y \in E_d$  and any sequence  $h_n \rightarrow 0$  as  $n \rightarrow \infty$

$$\Delta_{h_n, y}^1 v(t, x) := \frac{v(t, x + h_n y) - v(t, x)}{h_n} = \mathbf{E}\Delta_{h_n, y}^1 g(x + \eta_T(t)) = \mathbf{E}\Delta_{h_n, y}^1 g(\xi_T(t, x)).$$

Since  $g_y$  is continuous, the Mean Value Theorem yields

$$\Delta_{h_n, y}^1 g(\xi_T(t, x)) = \int_0^1 g_y(\xi_T(t, x) + rh_n y) dr = g_y(\xi_T(t, x)) + \theta h_n y,$$

for some  $\theta \in [0, 1]$ . Since  $g \in C^1(E_d)$ ,  $\Delta_{h_n, y}^1 g(\xi_T(t, x)) \rightarrow g_y(\xi_T(t, x))$  as  $n \rightarrow \infty$ . Furthermore, as  $n \rightarrow \infty$

$$\mathbf{E}\Delta_{h_n, y}^1 g(\xi_T(t, x)) \rightarrow \mathbf{E}g_y(\xi_T(t, x)). \tag{2.2}$$

To see this observe that

$$\begin{aligned} |\Delta_{h_n, y}^1 g(\xi_T(t, x))| &= |g_y(\xi_T(t, x) + \theta h_n y)| \\ &\leq |y|K(1 + |\xi_T(t, x) + \theta h_n y|^m) \\ &\leq 2^m K|y|(1 + |\xi_T(t, x)|^m + |\theta h_n y|^m) \\ &\leq N|y|(1 + |x|^m + \left| \int_t^T \sigma(r) d\mathbf{w}_r \right|^m + \left| \int_t^T b(r) dr \right|^m + |y|^m), \end{aligned}$$

where  $N = N(m, K)$ . By (2.1), the Burkholder-Davis-Gundy inequalities and the fact that  $\sigma, b$  are independent of  $\omega$ , the last expression above has finite expectation. Hence by [3, Lemma III.6.13 (f)], (2.2) holds. Since  $\{h_n\}$  was an arbitrary sequence converging to 0 as  $n \rightarrow \infty$ , we conclude

$$\lim_{h \rightarrow 0} \mathbf{E}\Delta_{h, y}^1 g(\xi_T(t, x)) = \mathbf{E}g_y(\xi_T(t, x)).$$

Thus  $v(t, x)$  is differentiable with respect to  $x$  and for any  $y \in E_d$ ,  $v_y(t, x) = \lim_{h \rightarrow 0} \mathbf{E}\Delta_{h, y}^1 g(\xi_T(t, x)) = \mathbf{E}g_y(\xi_T(t, x))$ . We now show that  $v(t, x)$  is twice differentiable with respect to  $x$ . By the above expression for  $v_y(t, x)$ , we have, for any  $\bar{y} \in E_d$

$$\frac{v_y(t, x + h\bar{y}) - v_y(t, x)}{h} = \mathbf{E}\Delta_{h, \bar{y}}^1 g_y(\xi_T(t, x)). \tag{2.3}$$

But since  $g_{y\bar{y}}$  is continuous, for any sequence  $h_n \rightarrow 0$  as  $n \rightarrow \infty$ , the Mean Value Theorem yields

$$\Delta_{h_n, \bar{y}}^1 g_y(\xi_T(t, x)) = \int_0^1 g_{y\bar{y}}(\xi_T(t, x) + rh_n \bar{y}) dr = g_{y\bar{y}}(\xi_T(t, x)) + \theta h_n \bar{y},$$

for some  $\theta \in [0, 1]$ . Since  $g \in C^2(E_d)$ ,  $\Delta_{h_n, \bar{y}}^1 g_y(\xi_T(t, x)) \rightarrow g_{y\bar{y}}(\xi_T(t, x))$  as  $n \rightarrow \infty$ . By the argument immediately following (2.2), except with  $|y|^2 + |\bar{y}|^2$  in place of  $|y|$  and using the growth condition on  $|g_{(y)(\bar{y})}(x)|$ , we see that  $|\Delta_{h_n, \bar{y}}^1 g_y(\xi_T(t, x))|$  is bounded above (independently of  $n$ ) by a random variable which has finite expectation. Hence

$$\mathbf{E}\Delta_{h_n, \bar{y}}^1 g_y(\xi_T(t, x)) \rightarrow \mathbf{E}g_{y\bar{y}}(\xi_T(t, x)) \quad \text{as } n \rightarrow \infty.$$

Since  $\{h_n\}$  was an arbitrary sequence converging to 0 as  $n \rightarrow \infty$ ,

$$\lim_{h \rightarrow 0} \mathbf{E} \Delta_{h, \bar{y}}^1 g_y(\xi_T(t, x)) = \mathbf{E} g_{y\bar{y}}(\xi_T(t, x)).$$

Thus by (2.3),  $v_{y\bar{y}}(t, x)$  exists and since  $y, \bar{y} \in E_d$  were arbitrary,  $v(t, x)$  is twice differentiable with respect to  $x$  and

$$v_{y\bar{y}}(t, x) = \lim_{h \rightarrow 0} \mathbf{E} \Delta_{h, \bar{y}}^1 g_y(\xi_T(t, x)) = \mathbf{E} g_{y\bar{y}}(\xi_T(t, x)).$$

We now show the continuity of  $v_{y\bar{y}}(t, x)$  in  $(t, x)$ . To this end, fix  $(t, x)$  and let  $t^n \rightarrow t^+, x^n \rightarrow x$ . It suffices to show  $v_{y\bar{y}}(t^n, x^n) \rightarrow v_{y\bar{y}}(t, x)$ . We have

$$|v_{y\bar{y}}(t^n, x^n) - v_{y\bar{y}}(t, x)| \leq \mathbf{E} |g_{y\bar{y}}(\xi_T(t^n, x^n)) - g_{y\bar{y}}(\xi_T(t, x))|. \quad (2.4)$$

Observe that  $\xi_T(t^n, x^n) \xrightarrow{P} \xi_T(t, x)$  and since  $g_{y\bar{y}}$  is continuous,  $g_{y\bar{y}}(\xi_T(t^n, x^n)) \xrightarrow{P} g_{y\bar{y}}(\xi_T(t, x))$ . Since  $|g_{y\bar{y}}(\xi_T(t^n, x^n))| \leq \eta$  with  $\mathbf{E}\eta < \infty$ , the right hand side of (2.5) tends to zero as  $n \rightarrow \infty$ . The details are as follows. To see that  $\xi_T(t^n, x^n) \xrightarrow{P} \xi_T(t, x)$ , observe that

$$\begin{aligned} & |\xi_T(t^n, x^n) - \xi_T(t, x)| \\ & \leq |x^n - x| + \left| \int_{t^n}^T \sigma(r) d\mathbf{w}_r - \int_t^T \sigma(r) d\mathbf{w}_r \right| + \left| \int_{t^n}^T b(r) dr - \int_t^T b(r) dr \right|. \end{aligned} \quad (2.5)$$

The middle summand tends to zero in probability as  $n \rightarrow \infty$  by [3, Theorem III.6.6] and the fact that

$$\int_0^T \|I_{t^n \leq r} \sigma(r) - I_{t \leq r} \sigma(r)\|^2 dr = \int_0^T \|\sigma(r)\|^2 I_{t \leq r < t^n} dr \rightarrow 0 \quad \text{as } n \rightarrow \infty$$

by (2.1) and the Dominated Convergence Theorem. The third summand on the right hand side of (2.5) tends to zero by the Dominated Convergence Theorem.

Since  $x^n \rightarrow x$ , we have  $\xi_T(t^n, x^n) \xrightarrow{P} \xi_T(t, x)$ . Since  $g_{y\bar{y}}(x)$  is continuous,

$$g_{y\bar{y}}(\xi_T(t^n, x^n)) \xrightarrow{P} g_{y\bar{y}}(\xi_T(t, x)),$$

by [3, Theorem III.6.13 (c)]. Finally,

$$\begin{aligned} & |g_{y\bar{y}}(\xi_T(t^n, x^n))| \\ & \leq K(|y|^2 + |\bar{y}|^2)(1 + |\xi_T(t^n, x^n)|^m) \\ & \leq 3^m K(|y|^2 + |\bar{y}|^2) \left\{ 1 + |x^n|^m + \left| \int_{t^n}^T \sigma(r) d\mathbf{w}_r \right|^m + \left| \int_{t^n}^T b(r) dr \right|^m \right\}. \end{aligned} \quad (2.6)$$

Since

$$\left| \int_{t^n}^T \sigma(r) d\mathbf{w}_r \right|^m \leq 2^m \sup_s \left| \int_0^{s \wedge T} \sigma(r) d\mathbf{w}_r \right|^m$$

as  $x^n \rightarrow x$  and  $\left| \int_{t^n}^T b(r) dr \right|^m \leq \left( \int_0^T |b(r)| dr \right)^m$ , the right hand side of (2.6) is bounded uniformly in  $n$  by a random variable, which, by the Burkholder-Davis-Gundy inequalities and (2.1), has finite expectation. Hence, by [3, Theorem III.6.13 (f)],

$$\mathbf{E} |g_{y\bar{y}}(\xi_T(t^n, x^n)) - g_{y\bar{y}}(\xi_T(t, x))| \rightarrow 0 \quad \text{as } n \rightarrow \infty$$

and hence by (2.4),  $v_{y\bar{y}}(t^n, x^n) \rightarrow v_{y\bar{y}}(t, x)$ .  $\square$

The proof that  $v(t, x)$  and  $v_y(t, x)$  are continuous in  $\bar{H}_T$  follow same the technique shown here, except we use the respective assumptions  $|g(x)|, |g_y(x)| \leq K(1+|x|^m)$ . Observe that by (2.6) and the Burkholder-Davis-Gundy inequalities, we obtain the following estimate, which holds for  $(t, x) \in \bar{H}_T$

$$\begin{aligned} & \|v_{xx}(t, x)\| \\ & \leq N(d, m, K) \left\{ 1 + |x|^m + \left( \int_t^T \|\sigma(r)\|^2 dr \right)^{m/2} + \left( \int_t^T |b(r)| dr \right)^m \right\}. \end{aligned} \tag{2.7}$$

If in addition,  $\sigma, b$  satisfy  $\sup_{t \leq T} (\|\sigma(t)\| + |b(t)|) \leq K$ , inequality (2.7) yields, with  $N_1 = N_1(d, m, K)$

$$\begin{aligned} \|v_{xx}(t, x)\| & \leq 2N(1 \vee K^m)(1 + |x|^m) \{1 + (T - t)^m\} \\ & \leq 4N(1 \vee K^m)(1 + |x|^m)e^{(T-t)m} \\ & \leq N_1(1 + |x|)^m e^{N_1(T-t)}. \end{aligned} \tag{2.8}$$

The following lemma appears in [3, p. 195]. We will use this lemma and the fact that  $v, v_x, v_{xx}$  are continuous in  $(t, x)$  to show that when  $\sigma(t), b(t)$  are bounded,  $v(t, x)$  is differentiable with respect to  $t$  for almost every  $t \in [0, T]$ .

**Lemma 2.2.** *Let  $\xi_s(t, x) = x + \int_t^s \sigma(r) d\mathbf{w}_r + \int_t^s b(r) dr$ , where  $\sup_{t \leq T} (\|\sigma(t)\| + |b(t)|) \leq K$ . For  $\epsilon > 0$  and  $(t, x) \in Q$ , let*

$$\tau_\epsilon(t, x) = \inf\{s \geq t : (s, \xi_s(t, x)) \notin Q_\epsilon(t, x)\},$$

where  $Q_\epsilon(t, x) = (t - \epsilon^3, t + \epsilon^3) \times B_\epsilon(x)$ . Then for any compact set  $\Gamma \subset Q_+ := Q \cap \{t \geq 0\}$ ,

$$\epsilon^{-3} P\{\tau_\epsilon(t, x) - t < \epsilon^3\} \rightarrow 0, \quad \epsilon^{-3} \mathbf{E}[\tau_\epsilon(t, x) - t] \rightarrow 1,$$

uniformly in  $(t, x) \in \Gamma$ , as  $\epsilon \rightarrow 0^+$ .

**Theorem 2.3.** *Under the hypotheses of Theorem 2.1 suppose that  $\sup_{t \leq T} (\|\sigma(t)\| + |b(t)|) \leq K$ . Then for any  $x \in E_d$ , the function  $v(t, x) = \mathbf{E}g(\xi_T(t, x))$  is differentiable with respect to  $t$  for almost every  $t \in [0, T]$ .*

*Proof.* Fix any  $(t, x) \in H_T$  and choose  $\epsilon$  so small that  $t + \epsilon^3 < T$ . Since absolutely continuous functions of a single real variable are differentiable almost everywhere, it suffices to show that  $v(t, x)$  is Lipschitz in  $t$ . By the strong Markov property we can write

$$v(t, x) = \mathbf{E}v(\tau_\epsilon(t, x), \xi_{\tau_\epsilon(t, x)}(t, x)), \tag{2.9}$$

which we henceforth abbreviate as  $\mathbf{E}v(\tau_\epsilon, \xi_{\tau_\epsilon})$ . By Itô's formula applied to the  $C^2$  function (of  $x$ )  $v(t + \epsilon^3, \cdot)$ , we have

$$\begin{aligned} & v(t, x) - v(t + \epsilon^3, x) \\ & = \mathbf{E}[v(\tau_\epsilon, \xi_{\tau_\epsilon}) - v(t + \epsilon^3, \xi_{\tau_\epsilon})] + \mathbf{E}[v(t + \epsilon^3, \xi_{\tau_\epsilon}) - v(t + \epsilon^3, \xi_t)] \\ & = \mathbf{E} I_{\tau_\epsilon < t + \epsilon^3} [v(\tau_\epsilon, \xi_{\tau_\epsilon}) - v(t + \epsilon^3, \xi_{\tau_\epsilon})] + \mathbf{E} \int_t^{\tau_\epsilon} L_r v(t + \epsilon^3, \xi_r) dr \end{aligned} \tag{2.10}$$

Certainly  $|v(\tau_\epsilon, \xi_{\tau_\epsilon}) - v(t + \epsilon^3, \xi_{\tau_\epsilon})| \leq 2 \sup_{[t, t + \epsilon^3] \times \overline{B_\epsilon(x)}} |v|$ . We recall that  $v, v_x, v_{xx}$  are continuous and hence bounded in any compact set. By definition,  $L_r v(t +$

$\epsilon^3, \xi_r) = \frac{1}{2} \operatorname{tr}[a(r)v_{xx}(t+\epsilon^3, \xi_r)] + b(r) \cdot v_x(t+\epsilon^3, \xi_r)$ . From the elementary inequality  $|\operatorname{tr}[a \cdot m]| \leq \|a\| \|m\|$  and the fact that  $\|\sigma(t)\| + |b(t)| \leq K$ , we get, for  $r \in [t, \tau_\epsilon]$ ,

$$\begin{aligned} |L_r v(t + \epsilon^3, \xi_r)| &\leq \frac{K^2}{2} \|v_{xx}(t + \epsilon^3, \xi_r)\| + K |v_x(t + \epsilon^3, \xi_r)| \\ &\leq N(K) \left( \sup_{B_\epsilon(x)} \|v_{xx}(t + \epsilon^3, \cdot)\| + \sup_{B_\epsilon(x)} |v_x(t + \epsilon^3, \cdot)| \right). \end{aligned} \quad (2.11)$$

So in any small closed cylinder  $\tilde{Q} \supset [t, t + \epsilon^3] \times \overline{B_\epsilon(x)}$ , we have, by (2.10) and Lemma 2.2, for sufficiently small  $\epsilon$ ,

$$\begin{aligned} &|v(t, x) - v(t + \epsilon^3, x)| \\ &\leq 2 \sup_{\tilde{Q}} |v| \cdot P\{\tau_\epsilon - t < \epsilon^3\} + N(K) \left( \sup_{\tilde{Q}} \|v_{xx}\| + \sup_{\tilde{Q}} |v_x| \right) \mathbf{E}[\tau_\epsilon - t] \\ &\leq N_1(K) \left( \sup_{\tilde{Q}} |v| + \sup_{\tilde{Q}} |v_x| + \sup_{\tilde{Q}} \|v_{xx}\| \right) \epsilon^3. \end{aligned}$$

Since  $t, \epsilon$  were arbitrary (such that  $t + \epsilon^3 < T$ ), we get, for any  $s, t \in [0, T]$  and any fixed  $x \in E_d$ ,

$$|v(t, x) - v(s, x)| \leq N_2 |t - s|,$$

where  $N_2$  is independent of  $s, t, x$ . Hence the generalized derivative  $\frac{\partial v}{\partial t}$  exists and  $|\frac{\partial v}{\partial t}(t, x)| \leq N_2$ .  $\square$

We will now show that the function  $v(t, x) = \mathbf{E}g(\xi_T(t, x))$  satisfies the Kolmogorov equation almost everywhere in  $H_T$ , under the assumptions of Theorem 2.3. Our main tool will be the Aleksandrov-Busemann-Feller (ABF) theorem (see [4, Theorem 1.1]) for continuous functions which are convex in  $x$  and non-increasing in  $t$ .

**Theorem 2.4** (Aleksandrov-Busemann-Feller). *Let  $u(t, x)$  be convex in  $x$ , non-increasing in  $t$  and continuous in  $\bar{H}_T$ . Let  $P(s, x, t, y) = u(s, x) + u_s^{(0)}(s, x)t + u_x(s, x) \cdot y + \frac{1}{2}y^* u_{xx}^{(0)}(s, x)y$ , where  $u_s^{(0)}, u_{x^i x^j}^{(0)}$  denote generalized derivatives. Then for almost all  $(s, x) \in E_{d+1}$ ,  $u(s + t, x + y) = P(s, x, t, y) + o(|t| + |y|^2)$  as  $(t, y) \rightarrow (0, 0)$ .*

Equivalently, for almost all  $(t_0, x_0) \in E_{d+1}$ ,  $u(t, x) = P_{(t_0, x_0)}(t, x) + o(|t - t_0| + |x - x_0|^2)$  as  $(t, x) \rightarrow (t_0, x_0)$ , where  $P_{(t_0, x_0)}(t, x) = u(t_0, x_0) + u_t^{(0)}(t_0, x_0)(t - t_0) + u_x(t_0, x_0) \cdot (x - x_0) + \frac{1}{2}(x - x_0)^* u_{xx}^{(0)}(t_0, x_0)(x - x_0)$ . We want to apply the ABF theorem to a variant of  $v$ . To this end, note that by (2.6), for any  $l \in E_d$ , we have

$$|v_{(l)(l)}(t, x)| \leq \mathbf{E} |g_{(l)(l)}(\xi_T(t, x))| \leq N e^{N(T-t)} (1 + |x|)^m,$$

where  $N = N(m, K)$ . Direct calculation shows that for any  $l, x \in E_d$ ,  $(m + 2)2^{-\frac{m}{2}} (1 + |x|)^m \leq [(1 + |x|^2)^{\frac{m}{2} + 1}]_{(l)(l)}$ . Hence

$$|v_{(l)(l)}(t, x)| \leq \frac{N e^{N(T-t)} 2^{\frac{m}{2}}}{m + 2} [(1 + |x|^2)^{\frac{m}{2} + 1}]_{(l)(l)} \leq N e^{N(T-s)} [(1 + |x|^2)^{\frac{m}{2} + 1}]_{(l)(l)}$$

which yields

$$0 \leq \left( v(t, x) + N e^{N(T-t)} (1 + |x|^2)^{\frac{m}{2} + 1} \right)_{(l)(l)} \quad \forall (t, x) \in H_T, l \in E_d.$$

That is, the function  $v(t, x) + N e^{N(T-t)} (1 + |x|^2)^{\frac{m}{2} + 1}$  is convex in  $x$ . We may also consider this function to be decreasing in  $t$  by the following argument. By Lemma

2.2, the first summand on the right hand side of (2.10) is  $o(\epsilon^3)$  as  $\epsilon \rightarrow 0$ . By the continuity of  $v_{xx}(t, x), v_x(t, x)$ , the last factor on the right hand side of (2.11) tends to  $\|v_{xx}(t, x)\| + |v_x(t, x)|$  as  $\epsilon \rightarrow 0$ . Since the estimate  $|v_x(t, x)| \leq Ne^{N(T-t)}(1+|x|)^m$  also holds, dividing (2.10) by  $\epsilon^3$ , letting  $\epsilon \rightarrow 0$ , using (2.8) and applying the second result in Lemma 2.2, we get for almost every  $t \in [0, T]$  and any  $x \in E_d$

$$\left| \frac{\partial v}{\partial t}(t, x) \right| \leq Ne^{N(T-t)}(1+|x|)^m \leq Ne^{N(T-t)}(1+|x|^2)^{\frac{m}{2}+1}, \tag{2.12}$$

where  $N = N(d, m, K)$ . From (2.12) it follows, as before, that for some  $N = N(d, m, K)$ ,  $v(t, x) + Ne^{N(T-t)}(1+|x|^2)^{\frac{m}{2}+1} := v + v_0$  is decreasing in  $t$ .

**Theorem 2.5.** *Under the assumptions of Theorem 2.3, the function  $v(t, x) = \mathbf{E}g(\xi_T(t, x))$  satisfies the Kolmogorov equation almost everywhere in  $H_T$ .*

*Proof.* Since the ABF theorem holds for the function  $v + v_0$  and  $v_0$  is smooth, the ABF theorem also holds for  $v$ . Since  $v$  has continuous second derivatives (by Theorem 2.1),  $v_{xx}^{(0)} = v_{xx}$  almost everywhere. So fix any  $(t, x) \in H_T$  for which the assertion of the ABF theorem holds for  $v$ ,  $v_{xx}^{(0)}(t, x) = v_{xx}(t, x)$  and  $t$  is in the Lebesgue set of the operator  $L_s \equiv \frac{1}{2}a^{ij}(s)\frac{\partial^2}{\partial x^i \partial x^j} + b^i(s)\frac{\partial}{\partial x^i}$ . By the strong Markov property,  $v(t, x) = \mathbf{E}v(\tau_\epsilon, \xi_{\tau_\epsilon})$ , where  $\tau_\epsilon(t, x)$  is as in Lemma 2.2. By the ABF theorem,  $v(\tau_\epsilon, \xi_{\tau_\epsilon}) = P_{(t,x)}(\tau_\epsilon, \xi_{\tau_\epsilon}) + o(|\tau_\epsilon - t| + |\xi_{\tau_\epsilon} - x|^2)$  as  $\epsilon \rightarrow 0$ . Since  $\xi_t(t, x) = x$  and  $P_{(t,x)}(t, x) = v(t, x)$ , applying Itô's formula to the paraboloid  $P_{(t,x)}$  yields

$$0 = \mathbf{E} \int_t^{\tau_\epsilon} (L_r P + \frac{\partial P}{\partial r})(r, \xi_r) dr + \mathbf{E}[o(|\tau_\epsilon - t| + |\xi_{\tau_\epsilon} - x|^2)]. \tag{2.13}$$

Since  $0 \leq \tau_\epsilon - t \leq \epsilon^3$ , the estimates  $\mathbf{E}|\xi_{\tau_\epsilon} - x|^p \leq N(p, K)\epsilon^{\frac{3p}{2}}(1 + \epsilon^{\frac{3p}{2}})$  and  $|v(t, x)| \leq N(T, m, K)(1+|x|)^m$  imply that the second summand on the right of (2.13) is  $o(\epsilon^3)$ . Let us write the first summand on the right of (2.13) as

$$\mathbf{E}I_{\tau_\epsilon < t + \epsilon^3} \int_t^{\tau_\epsilon} (L_r P + \frac{\partial P}{\partial r})(r, \xi_r) dr + \mathbf{E}I_{\tau_\epsilon = t + \epsilon^3} \int_t^{t + \epsilon^3} (L_r P + \frac{\partial P}{\partial r})(r, \xi_r) dr. \tag{2.14}$$

Since the coefficients of  $L_r$  are uniformly bounded and  $r \in [t, \tau_\epsilon]$  implies  $|\xi_r - x| < \epsilon$ , the integrand in the first summand of (2.14) satisfies

$$\left| (L_r P + \frac{\partial P}{\partial r})(r, \xi_r) \right| \leq (K^2 + K\epsilon)\|v_{xx}(t, x)\| + K|v_x(t, x)| + |v_t^{(0)}(t, x)|.$$

Since  $\epsilon \in (0, 1)$ ,

$$\begin{aligned} & \left| \mathbf{E}I_{\tau_\epsilon < t + \epsilon^3} \int_t^{\tau_\epsilon} (L_r P + \frac{\partial P}{\partial r})(r, \xi_r) dr \right| \\ & \leq N(K)(\|v_{xx}(t, x)\| + |v_x(t, x)| + |v_t^{(0)}(t, x)|) \cdot P\{\tau_\epsilon < t + \epsilon^3\}, \end{aligned}$$

and hence the first expectation in (2.14) is  $o(\epsilon^3)$  by Lemma 2.2. Dividing the second expectation in (2.14) by  $\epsilon^3$  and evaluating it explicitly yields

$$\begin{aligned} & \mathbf{E}I_{\tau_\epsilon = t + \epsilon^3} \frac{1}{\epsilon^3} \int_t^{t + \epsilon^3} (L_r v(t, x) + v_t^{(0)}(t, x)) dr \\ & + \mathbf{E}I_{\tau_\epsilon = t + \epsilon^3} \frac{1}{\epsilon^3} \int_t^{t + \epsilon^3} b(r)^* v_{xx}(t, x)(\xi_r - x) dr. \end{aligned} \tag{2.15}$$



Since  $t$  is a Lebesgue point for  $L_s$ , we have (almost surely)

$$I_{\tau_\epsilon=t+\epsilon^3} \frac{1}{\epsilon^3} \int_t^{t+\epsilon^3} \left( L_r v(t, x) + v_t^{(0)}(t, x) \right) dr \rightarrow L_t v(t, x) + v_t^{(0)}(t, x) \quad \text{as } \epsilon \rightarrow 0$$

and since

$$\begin{aligned} & \left| I_{\tau_\epsilon=t+\epsilon^3} \frac{1}{\epsilon^3} \int_t^{t+\epsilon^3} \left( L_r v(t, x) + v_t^{(0)}(t, x) \right) dr \right| \\ & \leq K^2 \|v_{xx}(t, x)\| + K |v_x(t, x)| + |v_t^{(0)}(t, x)|, \end{aligned}$$

the first expectation in (2.15) converges to  $L_t v(t, x) + v_t^{(0)}(t, x)$  as  $\epsilon \rightarrow 0$ . The second expectation in (2.15) converges to 0 as  $\epsilon \rightarrow 0$ . Recalling that  $0 \leq \tau_\epsilon - t \leq \epsilon^3$  and that  $r \in [t, \tau_\epsilon]$  implies  $|\xi_r - x| < \epsilon$ , we immediately get the bound

$$\left| I_{\tau_\epsilon=t+\epsilon^3} \frac{1}{\epsilon^3} \int_t^{t+\epsilon^3} b(r)^* v_{xx}(t, x) (\xi_r - x) dr \right| \leq \frac{1}{\epsilon^3} \|v_{xx}(t, x)\| K \epsilon^4 = \|v_{xx}(t, x)\| K \epsilon.$$

Hence dividing (2.13) by  $\epsilon^3$  and letting  $\epsilon \rightarrow 0$ , we get  $L_t v(t, x) + v_t^{(0)}(t, x) = 0$ .  $\square$

### 3. FUNDAMENTAL SOLUTIONS OF THE KOLMOGOROV EQUATION - THE ANALYTIC APPROACH

Even the “analytic” proof that  $v(t, x) = \mathbf{E}g(\xi_T(t, x))$  is a solution of the Kolmogorov equation relies on the well known probabilistic fact that since coefficients  $\sigma(t)$ ,  $b(t)$  are independent of  $\omega$ , the vector  $\xi_T(t, x)$  is a Gaussian vector with parameters  $(x + \int_t^T b(r) dr, \int_t^T a(r) dr)$ . Hence, the distribution  $P\xi_T(t, x)^{-1}$  has density function

$$p(T, t, y) = \frac{e^{-\frac{1}{2} \langle C^{-1}(t)(y-x-\int_t^T b(r)dr), y-x-\int_t^T b(r)dr \rangle}}{(2\pi)^{\frac{d}{2}} \sqrt{\det C(t)}},$$

where  $C(t) = C_T(t) = \int_t^T a(r) dr$ . From this, it follows that a solution to the problem

$$\begin{cases} \frac{1}{2} a^{ij}(t) v_{x^i x^j}(t, x) + b^i(t) v_{x^i}(t, x) + \frac{\partial v}{\partial t}(t, x) = 0 & \text{a. e. } t \in [0, T) \\ v(T, x) = g(x) & x \in E_d \end{cases} \quad (3.1)$$

is given by

$$\begin{aligned} v(t, x) &= \mathbf{E}g(\xi_T(t, x)) \\ &= \int_{E_d} g(y) P \xi_T^{-1}(t, x) (dy) \\ &= \int_{E_d} g(y) \frac{e^{-\frac{1}{2} \langle C^{-1}(t)(y-x-\int_t^T b(r)dr), y-x-\int_t^T b(r)dr \rangle}}{(2\pi)^{\frac{d}{2}} \sqrt{\det C(t)}} dy, \end{aligned} \quad (3.2)$$

where  $a(r) = \sigma(r)\sigma^*(r)$  is non-degenerate. We prove this in Theorem 3.1 below, for slowly increasing  $g \in C^0(E_d)$ . Viewed analytically, since the function

$$p(T, t, x) = \frac{e^{-\frac{1}{2} \langle C^{-1}(t)(x+\int_t^T b(r)dr), x+\int_t^T b(r)dr \rangle}}{(2\pi)^{\frac{d}{2}} \sqrt{\det C(t)}} \quad (3.3)$$

is a fundamental solution (in  $x$ ) of the equation  $L_t p(t, x) + \frac{\partial p}{\partial t}(t, x) = 0$  a.e.  $t \in [0, T)$ , all  $x \neq -\int_t^T b(r)dr$ , where  $L_t \equiv \frac{1}{2}a^{ij}(t)\frac{\partial^2}{\partial x^i \partial x^j} + b^i(t)\frac{\partial}{\partial x^i}$ , a solution to (3.1) will be given by the convolution

$$\begin{aligned} v(t, x) &= [g * p(T, t, \cdot)](x) \\ &= \int_{E_d} g(y) p(T, t, x - y) dy \\ &= \int_{E_d} g(y) \frac{e^{-\frac{1}{2}\langle C^{-1}(t)(x-y+\int_t^T b(r)dr), x-y+\int_t^T b(r)dr \rangle}}{(2\pi)^{\frac{d}{2}} \sqrt{\det C(t)}} dy, \end{aligned}$$

providing, of course, we can differentiate under the integral sign. Regarding notation, by *fundamental solution*, we mean that for all  $t \in [0, T)$ ,  $p(T, t, x)$  is infinitely differentiable in  $x$  and  $\int_{E_d} p(T, t, x) dx = 1$ .

By Lebesgue's differentiation theorem,  $p(T, t, x)$  in (2) is differentiable with respect to  $t$ , only in the *almost everywhere* sense. This is in contrast to the case where  $a(t) = I_d, b(t) = b(const.)$  and the Kolmogorov equation is simply  $\frac{1}{2}\Delta u(t, x) + b \cdot u_x(t, x) + \frac{\partial u}{\partial t}(t, x) = 0$  for all  $(t, x) \in H_T$ . In this case,  $p(T, t, x) = (2\pi(T - t))^{-\frac{d}{2}} e^{-\frac{|x+b(T-t)|^2}{2(T-t)}}$  is infinitely differentiable in both  $t$  and  $x$ .

**Theorem 3.1.** *For  $t \in [0, T]$  and  $x \in E_d$  and  $s \in [t, T]$ , let  $\xi_s(t, x) = x + \int_t^s \sigma(r) dw_r + \int_t^s b(r) dr$ , where  $\sup_{t \leq T} (\|\sigma(t)\| + |b(t)|) \leq K$ . Assume  $\exists \delta > 0$  for which  $\delta I_d \leq a(t)$ , for all  $t \in [0, T]$ , where  $a(t) = \sigma(t)\sigma^*(t)$ . Then for  $p(T, t, x)$  as in (2) and  $g$  continuous and slowly increasing, the function*

$$v(t, x) = \mathbf{E}g(\xi_T(t, x)) = \int_{E_d} g(y) p(T, t, x - y) dy$$

satisfies the Kolmogorov equation  $\frac{1}{2}a^{ij}(t)v_{x^i x^j}(t, x) + b^i(t)v_{x^i}(t, x) + \frac{\partial v}{\partial t}(t, x) = 0$  a.e.  $t \in [0, T)$  and any  $x \in E_d$ .

*Proof.* Direct calculation shows that for almost every  $t \in [0, T)$  and any  $x \neq -\int_t^T b(r)dr \in E_d$ ,  $p(T, t, x)$  is a solution of the Kolmogorov equation. Thus we need only show that we can differentiate under the integral sign. Omitting the constant factor of  $(2\pi)^{-d/2}$ , direct calculation shows that for almost every  $t \in [0, T)$ , with  $z = y - x$  and  $\eta_t := \int_t^T b(r) dr$ ,

$$\begin{aligned} &\frac{\partial p}{\partial t}(T, t, x - y) \\ &= \frac{e^{-\frac{1}{2}\langle C^{-1}(t)(z-\eta_t), z-\eta_t \rangle}}{2\sqrt{\det C(t)}} \left\{ \text{tr}[a(t)C^{-1}(t)] - \langle C^{-1}(t) a(t) C^{-1}(t)(z - \eta_t), z - \eta_t \rangle \right. \\ &\quad \left. + 2\langle C^{-1}(t)(y - x), b(t) \rangle + 2\langle C^{-1}(t) b(t), \eta_t \rangle \right\} \end{aligned}$$

and hence

$$\begin{aligned} &\left| \frac{\partial p}{\partial t}(T, t, x - y) \right| \\ &\leq \frac{e^{-\frac{1}{2}\langle C^{-1}(t)(z-\eta_t), z-\eta_t \rangle}}{\sqrt{\det C(t)}} \left\{ \|a(t)\| \|C^{-1}(t)\| \right. \\ &\quad \left. + \|C^{-1}(t) a(t) C^{-1}(t)\| |z - \eta_t|^2 + \|C^{-1}(t)\| |z| |b(t)| + \|C^{-1}(t)\| |b(t)| |\eta_t| \right\}. \end{aligned}$$

Since  $\sup_{t \leq T} (\|\sigma(t)\| + |b(t)|) \leq K$  and  $\|ab\| \leq \|a\| \|b\|$ ,  $\|a(t)\| = \|\sigma(t)\sigma^*(t)\| \leq K^2$ . From the estimate  $\|C(t)\| \leq \sqrt{T-t} \sqrt{\int_t^T \|a(r)\|^2 dr}$ , we have  $\|C(t)\| \leq K^2(T-t)$ . Moreover, by the uniform non-degeneracy condition  $\delta|\lambda|^2 \leq a^{ij}(t)\lambda^i\lambda^j$ , which holds for all  $t \in [0, T]$  and all  $\lambda \in E_d$ , we get  $\|C^{-1}(t)\| \leq \frac{\sqrt{d}}{\delta(T-t)}$ . We also have  $C^{ij}(t)\lambda^i\lambda^j \geq \delta|\lambda|^2(T-t)$ , from which it immediately follows that  $\det C(t) \geq [\delta(T-t)]^d$ . Obviously,  $|\eta_t| \leq K(T-t)$ . This gives

$$\begin{aligned} & \left| \frac{\partial p}{\partial t}(T, t, x-y) \right| \\ & \leq \frac{e^{-\frac{1}{2}\langle C^{-1}(t)(z-\eta_t), z-\eta_t \rangle}}{(\delta(T-t))^{d/2}} \\ & \times \left\{ \frac{K^2\sqrt{d}}{\delta(T-t)} + \frac{2dK^2}{\delta^2(T-t)^2} (|y-x|^2 + K^2(T-t)^2) + \frac{K\sqrt{d}}{\delta(T-t)} |x-y| + \frac{K^2\sqrt{d}}{\delta} \right\}. \end{aligned}$$

Similarly, the gradient and hessian of  $p(T, t, x-y)$  satisfy

$$p_x(T, t, x-y) = \frac{e^{-\frac{1}{2}\langle C^{-1}(t)(z-\eta_t), z-\eta_t \rangle}}{\sqrt{\det C(t)}} C^{-1}(t) \cdot (z-\eta_t)$$

$$\begin{aligned} & p_{xx}(T, t, x-y) \\ & = \frac{e^{-\frac{1}{2}\langle C^{-1}(t)(z-\eta_t), z-\eta_t \rangle}}{\sqrt{\det C(t)}} \{C^{-1}(t)(z-\eta_t)[C^{-1}(t)(z-\eta_t)]^* - C^{-1}(t)\}. \end{aligned}$$

Thus

$$\begin{aligned} |p_x(T, t, x-y)| & \leq \frac{e^{-\frac{1}{2}\langle C^{-1}(t)(z-\eta_t), z-\eta_t \rangle}}{(\delta(T-t))^{d/2}} \|C^{-1}(t)\| \cdot |z-\eta_t| \\ & \leq \frac{\sqrt{d} e^{-\frac{1}{2}\langle C^{-1}(t)(z-\eta_t), z-\eta_t \rangle}}{(\delta(T-t))^{d/2+1}} \{ |y-x| + K(T-t) \}, \end{aligned}$$

$$\begin{aligned} & \|p_{xx}(T, t, x-y)\| \\ & \leq \frac{e^{-\frac{1}{2}\langle C^{-1}(t)(z-\eta_t), z-\eta_t \rangle}}{(\delta(T-t))^{d/2}} \{ \|C^{-1}(t)\|^2 \cdot |z-\eta_t|^2 + \|C^{-1}(t)\| \} \\ & \leq \frac{e^{-\frac{1}{2}\langle C^{-1}(t)(z-\eta_t), z-\eta_t \rangle}}{(\delta(T-t))^{d/2}} \left\{ \frac{2d}{\delta^2(T-t)^2} (|y-x|^2 + K^2(T-t)^2) + \frac{\sqrt{d}}{\delta(T-t)} \right\}. \end{aligned}$$

To estimate the exponential term in each derivative, we use the inequality  $\frac{|z-\eta_t|^2}{K^2(T-t)} \leq \langle C^{-1}(t)(z-\eta_t), z-\eta_t \rangle$  and Young's inequality (twice):  $|z-\eta_t|^2 \geq ||z| - |\eta_t||^2 \geq \frac{1}{2}|z|^2 - |\eta_t|^2 \geq \frac{1}{2}|y-x|^2 - K^2(T-t)^2 \geq \frac{1}{4}|y|^2 - \frac{1}{2}|x|^2 - K^2(T-t)^2$  to conclude

$$e^{-\frac{1}{2}\langle C^{-1}(t)(z-\eta_t), z-\eta_t \rangle} \leq e^{-\frac{|y|^2}{8K^2(T-t)} + \frac{|x|^2}{4K^2(T-t)} + \frac{T-t}{2}}.$$

Denoting any of the derivatives  $p_t, p_x, p_{xx}$  by  $p'(T, t, x-y)$ , we see that

$$|p'(T, t, x-y)| \leq \frac{N \cdot e^{-\frac{|y|^2}{8K^2(T-t)} + \frac{|x|^2}{4K^2(T-t)} + \frac{T-t}{2}}}{(T-t)^{\frac{d}{2}+2}} q(T-t, |y-x|),$$

where  $N = N(\delta, d, K)$  and  $q(a, b)$  is a paraboloid in  $a$  and  $b$ . Hence if  $(t, x) \in [0, t_0] \times B_R$ , where  $0 \leq t_0 < T$ , then

$$|p'(T, t, x - y)| \leq \frac{N \cdot e^{-\frac{|y|^2}{8K^2T} + \frac{R^2}{4K^2(T-t_0)} + T}}{(T - t_0)^{\frac{d}{2} + 2}} q(T, |y| + R).$$

So if we require that  $|g(x)| \leq Ne^{\frac{|x|^2}{16K^2T}}$ , we see that the integrals  $\int_{E_d} g(y)p'(T, t, x - y) dy$  converge uniformly with respect to  $(t, x) \in [0, t_0] \times B_R$ . This implies  $v(t, x)$  is twice differentiable with respect to  $x$ , once differentiable with respect to  $t$  (almost everywhere) and its derivatives can be evaluated by differentiating under the integral sign. Since  $p(T, t, x - y)$  satisfies the Kolmogorov equation for almost every  $t \in [0, T]$ , so does  $v(t, x)$ .  $\square$

**Remark.** The above growth condition for  $g$  is obviously satisfied when  $g$  has polynomial growth,  $|g(x)| \leq K(1 + |x|^m)$ . Furthermore, direct calculation shows that for any  $d$ -dimensional multi-index  $\alpha$ , any derivative of  $p(T, t, x - y)$  with respect to  $x$  satisfies

$$|D_x^\alpha p(T, t, x - y)| \leq \frac{N \cdot e^{-\frac{|y-x|^2}{4K^2(T-t)} + \frac{T-t}{2}}}{(T - t)^{\frac{d}{2} + |\alpha|}} \cdot q_\alpha(T - t, |y - x|),$$

where  $N = N(\delta, d, K, |\alpha|)$  and  $q_\alpha(a, b)$  is a polynomial of degree less than or equal to  $|\alpha|$  in  $a$  and  $b$ , from which it follows, as above, that  $v(t, x)$  is infinitely differentiable with respect to  $x$ .

More generally, if  $c(t) \geq 0$  is bounded and measurable in  $[0, T]$  and we define  $\phi_s(t) = \int_t^s c(r) dr$ , the function  $\tilde{p}(T, t, x) := p(T, t, x)e^{-\phi_T(t)}$  is an infinitely differentiable solution (in  $x$ ) of the equation  $L_t u(t, x) - c(t)u(t, x) + \frac{\partial u}{\partial t}(t, x) = 0$  a.e.  $t \in [0, T]$ . Since  $[g * \tilde{p}(T, t, \cdot)](x) = e^{-\phi_T(t)} [g * p(T, t, \cdot)](x)$ , a solution to the problem

$$\begin{cases} \frac{1}{2} a^{ij}(t) v_{x^i x^j}(t, x) + b^i(t) v_{x^i}(t, x) - c(t)v(t, x) + \frac{\partial v}{\partial t}(t, x) = 0 \\ \text{a.e. } t \in [0, T], \text{ all } x \in E_d \\ v(T, x) = g(x) \quad x \in E_d \end{cases}$$

is given by

$$v(t, x) = e^{-\phi_T(t)} \mathbf{E}g(\xi_T(t, x)),$$

while if  $\int_0^T |f(r)|e^{-\phi_r(t)} dr < \infty$ , direct calculation shows that the function

$$v(t, x) = e^{-\phi_T(t)} \mathbf{E}g(\xi_T(t, x)) + \int_t^T f(r)e^{-\phi_r(t)} dr \tag{3.4}$$

satisfies

$$\begin{cases} \frac{1}{2} a^{ij}(t) v_{x^i x^j}(t, x) + b^i(t) v_{x^i}(t, x) - c(t)v(t, x) + f(t) + \frac{\partial v}{\partial t}(t, x) = 0 \\ \text{a.e. } t \in [0, T] \text{ all } x \in E_d \\ v(T, x) = g(x) \quad x \in E_d. \end{cases}$$

#### 4. PARABOLOID SOLUTIONS OF THE SIMPLEST TIME-MEASURABLE BELLMAN EQUATIONS

In this section, we prove a result about the payoff function for the Bellman equation in the simple case where the equation depends only on second derivatives and  $t$  and the coefficients are Borel measurable functions of  $t$ . Let  $A$  be a separable metric space, where for  $(\alpha, t) \in A \times [0, T]$ ,  $\sigma(\alpha, t)$  is a  $d \times d_1$  matrix and  $f^\alpha(t)$  is a function, both continuous in  $\alpha$  and Borel measurable in  $t$ . Now let  $(\Omega, \mathcal{F}, P)$  be a complete probability space on which  $(\mathbf{w}_t, \mathcal{F}_t)$  is a  $d_1$ -dimensional Wiener process. We consider the controlled diffusion process  $\xi_s(\alpha, t, x)$ , defined for  $s \in [0, T]$  by  $\xi_s(\alpha, t, x) = x + \int_0^s \sigma(\alpha_r, t+r) d\mathbf{w}_r$ , where  $t \in [0, T]$ ,  $x \in E_d$  are fixed and  $\alpha_t$  is a strategy in class  $U$ , that is, progressively measurable with values in  $A$ .

Suppose  $g \in C^2(E_d)$  and satisfies  $|g(x)|, |g_{(y)}(x)|, |g_{(y)(y)}(x)| \leq K(1 + |x|^m)$ ,  $\forall x, y \in E_d$ , where  $K, m$  are nonnegative constants. It is known [4] that if for any  $\alpha \in A$ ,  $f^\alpha, \sigma(\alpha, \cdot)$  are differentiable with respect to  $t$  with derivatives not exceeding  $K$ , then the payoff function

$$v(t, x) = \sup_{\alpha \in U} \mathbf{E} \left[ \int_0^{T-t} f^{\alpha_r}(r+t) dr + g(\xi_{T-t}^\alpha(t, x)) \right] \quad (4.1)$$

satisfies the Bellman equation

$$\sup_{\alpha \in A} \{a^{ij}(\alpha, t)v_{x^i x^j}(t, x) + f^\alpha(t)\} + \frac{\partial v}{\partial t}(t, x) = 0 \quad \text{a. e. } H_T, \quad v(T, x) = g(x).$$

In the special case where  $g$  is a paraboloid, the payoff function takes a very convenient form and clearly satisfies the Bellman equation under the weak assumption that  $\sup_{\alpha \in A} f^\alpha, \sup_{\alpha \in A} \sigma(\alpha, \cdot) \in L_1([0, T]), L_2([0, T])$ , respectively.

**Theorem 4.1.** *Let  $p(x)$  be any paraboloid defined on  $E_d$ , i.e.  $p(x) = \frac{1}{2}x^*mx + l \cdot x + l_0$ , where  $m \in E_{d^2}, l \in E_d, l_0 \in E_1$ . Then the probabilistic solution of the Bellman equation*

$$\begin{cases} \sup_{\alpha \in A} \{a^{ij}(\alpha, t)v_{x^i x^j}(t, x) + f^\alpha(t)\} + \frac{\partial v}{\partial t}(t, x) = 0 & \text{a.e. } t \in [0, T] \\ v(T, x) = p(x) & x \in E_d. \end{cases}$$

is given by

$$v(t, x) = p(x) + \int_t^T \sup_{\alpha \in A} \{\text{tr}[a(\alpha, r)m] + f^\alpha(r)\} dr. \quad (4.2)$$

*Proof.* From the theory of controlled diffusion processes [2], the probabilistic solution to this Bellman equation is the payoff function (4.1) with  $g = p$  and  $a(\alpha, t) = \frac{1}{2}\sigma(\alpha, t)\sigma(\alpha, t)^*$ . It immediately follows from Itô's formula that  $\forall \alpha \in U, t \in [0, T]$  and  $x \in E_d$ , we have

$$\mathbf{E}p(\xi_{T-t}^\alpha(t, x)) = p(x) + \mathbf{E} \int_0^{T-t} \text{tr}[a(\alpha_r, t+r)m] dr. \quad (4.3)$$

We give a more direct proof of (4.3) using Wald's identity. Writing  $\xi_{T-t}^\alpha = \xi_{T-t}^{\alpha*} m \xi_{T-t}^\alpha$ , we have  $p(\xi_{T-t}^\alpha(t, x)) = \frac{\xi_{T-t}^{\alpha*} m \xi_{T-t}^\alpha}{2} + l \cdot \xi_{T-t}^\alpha + l_0$  and

$$\xi_{T-t}^{\alpha*} m \xi_{T-t}^\alpha = \langle m \xi_{T-t}^\alpha, \xi_{T-t}^\alpha \rangle = \langle mx, x \rangle + 2\langle mx, \eta_{T-t}^{\alpha, t} \rangle + \langle m \eta_{T-t}^{\alpha, t}, \eta_{T-t}^{\alpha, t} \rangle,$$

where  $\eta_{T-t}^{\alpha,t} := \int_0^{T-t} \sigma(\alpha_r, t+r) d\mathbf{w}_r$ . Writing  $m = ODO^*$ , where  $D = (\lambda^i \delta^{ij})$ , we get

$$\langle m\eta_{T-t}^{\alpha,t}, \eta_{T-t}^{\alpha,t} \rangle = \langle ODO^* \eta_{T-t}^{\alpha,t}, \eta_{T-t}^{\alpha,t} \rangle = \langle Dz_{T-t}^{\alpha,t}, z_{T-t}^{\alpha,t} \rangle = \sum_{i=1}^d \lambda^i \left( z_{T-t}^{\alpha,t,i} \right)^2$$

where

$$z_{T-t}^{\alpha,t} := O^* \cdot \eta_{T-t}^{\alpha,t} = \int_0^{T-t} O^* \cdot \sigma(\alpha_r, t+r) d\mathbf{w}_r := \int_0^{T-t} \tilde{\sigma}(\alpha_r, t+r) d\mathbf{w}_r.$$

Orthogonality and the Wald identity yield

$$\mathbf{E} \left( z_{T-t}^{\alpha,t,i} \right)^2 = \mathbf{E} \sum_{k=1}^d \left( \int_0^{T-t} \tilde{\sigma}^{ik}(\alpha_r, t+r) d\mathbf{w}_r^k \right)^2 = \sum_{k=1}^d \mathbf{E} \int_0^{T-t} [\tilde{\sigma}^{ik}(\alpha_r, t+r)]^2 dr,$$

and hence

$$\begin{aligned} \mathbf{E} \langle m\eta_{T-t}^{\alpha,t}, \eta_{T-t}^{\alpha,t} \rangle &= \sum_{i=1}^d \lambda^i \sum_{k=1}^d \mathbf{E} \int_0^{T-t} [\tilde{\sigma}^{ik}(\alpha_r, t+r)]^2 dr \\ &= 2\mathbf{E} \int_0^{T-t} \text{tr}[a(\alpha_r, t+r)m] dr. \end{aligned}$$

By Wald's identity, we also have  $\mathbf{E} \langle mx, \eta_{T-t}^{\alpha,t} \rangle = 0$  and  $\mathbf{E}[l \cdot \xi_{T-t}^\alpha + l_0] = \mathbf{E}[l \cdot (x + \eta_{T-t}^{\alpha,t}) + l_0] = l \cdot x + l_0$ . Thus

$$\begin{aligned} \mathbf{E}p(\xi_{T-t}^\alpha(t, x)) &= \mathbf{E} \left[ \frac{\xi_{T-t}^{\alpha*} m \xi_{T-t}^\alpha}{2} + l \xi_{T-t}^\alpha + l_0 \right] \\ &= p(x) + \mathbf{E} \int_0^{T-t} \text{tr}[a(\alpha_r, t+r)m] dr. \end{aligned}$$

Therefore,

$$\begin{aligned} v(t, x) &= p(x) + \sup_{\alpha \in U} \mathbf{E} \left[ \int_0^{T-t} \text{tr}[a(\alpha_r, t+r)m] + f^{\alpha_r}(r+t) dr \right] \\ &= p(x) + \int_t^T \sup_{\alpha \in \mathcal{A}} \{ \text{tr}[a(\alpha, r)m] + f^\alpha(r) \} dr. \end{aligned}$$

□

This result is hardly a surprise since the second-order derivatives of any paraboloid are constant. Hence by Lebesgue's differentiation theorem, for any operator  $F(b, t)$  for which  $\int_0^T |F(b, t)| dt < \infty$ , the function

$$u(t, x) = p(x) + \int_t^T F(p_{xx}(x), r) dr$$

satisfies

$$\begin{cases} F(u_{xx}(t, x), t) + \frac{\partial u}{\partial t}(t, x) = 0 & \text{a.e. } t \in [0, T) \\ u(T, x) = p(x) & x \in E_d. \end{cases}$$

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